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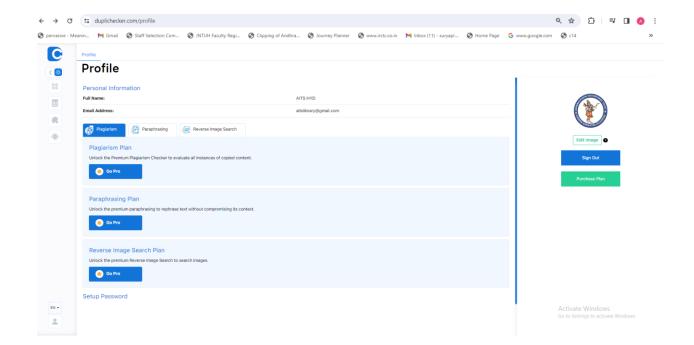
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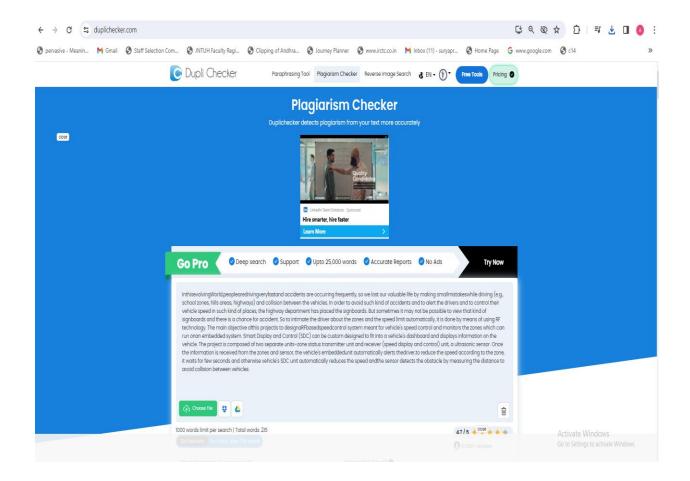
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SAMPLE PROJECT WORK IN PLAGIARISM CHECKER



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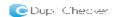
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RESULT REPORT OF PLAGIARISM CHECKER



PLAGIARISM SCAN REPORT



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InthisevolvingWorld,peoplearedrivingveryfastand accidents are occurring frequently, so we lost our valuable life by making smallmistakeswhile driving (e.g., school zones, hills areas, highways) and collision between the vehicles.

In order to avoid such kind of accidents and to alert the drivers and to control their vehicle speed in such kind of places, the highway department has placed the signboards.

But sometimes it may not be possible to view that kind of signboards and there is a chance for accident.

So to intimate the driver about the zones and the speed limit automatically, it is done by means of using RF technology. The main objective ofthis projectis to designaRFbasedspeedcontrol system meant for vehicle's speed control and monitors the zones which can run onan embedded system.

Smart Display and Control (SDC) can be custom designed to fit into a vehicle's dashboard and displays information on the vehicle.

The project is composed of two separate units—zone status transmitter unit and receiver (speed display and control) unit, a ultrasonic sensor.

Once the information is received from the zones and sensor, the vehicle's embeddedunit automatically alerts thedriver, to reduce the speed according to the zone, it waits for few seconds and otherwise vehicle's SDC unit automatically reduces the speed and the sensor detects the obstacle by measuring the distance to avoid collision between vehicles.

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highways) and collision between the vehicles. In order to avoid such kind of accidents and to alert the drivers and to control their vehicle speed in such kind of places, the highway department has placed the signboards. But sometimes it may not be possible to view that kind of signboards and there is a chance for accident. So

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P PSo to intimate the driver about the zones and the speed limit automatically, it is done by means of using RF technolog \checkmark y \checkmark . The main objective of this project is to design a P RF \checkmark based P speed control \checkmark system meant for vehicle's P speed control \checkmark and monitors the zones which can run on an embedded system.

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